Ryan Taylor Embedded Systems Engineer

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EDUCATION

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Bachelor of Engineering: Electrical and Computer Engineering 08/2020 - 05/2024 Vanderbilt University Nashville, Tennesse Minor: Computer Science 3.44/4.00 💼 PROFESSIONAL EXPERIENCE **Electrical Engineer** 08/2023 - Present Vanderbilt Aerospace Design Laboratory: NASA Student Launch 🛽 Nashville, Tennessee • Engineered an autonomous Unmanned Aerial Vehicle (UAV) capable of launching from a rocket and proficiently navigating and safely landing in an atmosphere-agnostic setting. Spearheaded the hardware and circuitry design for the drone, overseeing the integration of control systems and computer vision algorithms with LiDAR, IMU, motor controllers, and radio telemetry to enable seamless autonomous deployment. 05/2023 - 08/2023 **Controls Simulation Intern** Rolls-Royce North America 🖸 Indianapolis, Indiana · Performed behavioral analysis on a legacy Simulink engine model and correlated its output data to validate its fidelity with modern engine simulations used by Rolls-Royce. • Comprehensively understand the architecture of the AE3007N engine and how its electro-mechanical systems were emulated within the Simulink model. Revised plotting scripts and interpolation algorithms needed to correlate engine simulation datasets and implement robust UI elements to facilitate analysis 05/2022 - 08/2022 **Electronics Development Intern** Indianapolis, Indiana Rolls-Royce North America 🗹 • Administrated driver integration of an AVL dynamometer into the test stand control system in the Electric Power Lab to streamline testing operations and data acquisition. Modernized data aggregation systems by installing a private git server and establishing autonomous routines to log changes in configuration files on test stands for auditing purposes. Characterized electronic equipment to verify that they operated within specified threshold values and performed diagnostic testing to identify flaws in the structural design of devices in the event of failure **B** LEADERSHIP ACTIVITIES **Drive Control and Electrical Team Lead** 01/2021 - Present Vanderbilt Robotics Club: NASA Lunabotics Mining Competition Nashville, Tennesse • Innovated autonomous navigation capabilities through the development of localization algorithms and cutting-edge computer vision solutions, harnessing the potential of depth cameras, LiDAR technology, and ROS2 framework. Streamlined and enhanced the circuit topology of power management systems, optimizing them for compact robot chassis to ensure efficient drive control and sensor integration. 08/2021 - 05/2023 **Electrical and Programming Team Co-Lead** Vanderbilt Satellite Club Nashville, Tennessee • Launched weather balloon to validate preliminary designs and operating conditions for PCB circuit designs, sensory devices, and communication systems. Designed communications interface to connect weather balloon with ground operations, developing radio telemetry to broadcast sensory data on APRS website. 🖿 PERSONAL PROJECTS Electric Longboard 17 06/2020 - Present • Conceptualized and constructed a Dual-Motor Hub Electric Longboard, and assembled the longboard from individual components, achieving seamless operation under the control of a Bluetooth interface. Elevated design by upgrading the electric speed controller and battery to optimize motor performance and increase customization capabilities 08/2022 - 12/2022 Laser Tracking Robot 🛛 • Programmed a FreeNove robot to autonomously follow a user-guided laser, record its trajectory, and re-traverse the path it travels from its starting position. • Designed software architecture using threads, task synchronization and communication, and motor control functions 01/2021 - 05/2021 Maze-Solving Robot • Encoded a Polulu 3Pi Robot to navigate a maze then calculate the optimal path and traverse the maze a second time without making redundant traversals. Designed a control loop that allows the robot to follow a black line using infrared sensors and course correct itself if it veers off the path and record its position as it traverses the maze. SKILLS C/C++ Julia Python Bash React LTSpice ROS2 MATLAB/Simulink Autodesk Machine Learning